

Revision	Date
Initial Release	Dec 27, 2018
Rev 1	Jan 14, 2019
Added DD2 instructions	Feb 6, 2019



HONDATA KPro, KPro2 & KPro3 ECU's to AEM CD-5 & CD-7 Displays

Supported Devices

KPro KPro2 KPro3

Running in PRB, PNF, PRD, PRC and PND ECUs.

Required Interface Device

AEM 30-2229, Serial2CAN Adapter, Hondata KPro



Supported Channels

The CD-5 & CD-7 displays support the following 30 channels transmitted by the KPro ECUs:

EngineSpeed (RPM)	Reverse_Lockout_Status (On/Off)
VehicleSpeed (KPH)	Brake_Switch_Status (On/Off)
GearPosCalculated	AC_Switch_Status (On/Off)
ECUBatteryVoltage (V)	AC_Clutch_Status (On/Off)
IntakeManifoldAirTemp (C)	SCS_Status (On/Off)
CoolantTemp (C)	EPS_PSP_Status (On/Off)
ThrottlePos (%)	VTEC_Oil_Pressure_Status (On/Off)
IntakeManifoldAirPress (kPa)	VTEC_Sol_1_Status (On/Off)
FuelInjPulsewidth (mS)	VTEC_Sol_2_Status (On/Off)
IgnitionTiming (deg)	MIL_Status (On/Off)
AFR (EQ)	Nitrous1_Arm_Status (On/Off)
AFR (LA)	Nitrous2_Arm_Status (On/Off)
KnockCount	Nitrous1_Active_Status (On/Off)
CamIntakePos (Deg)	Nitrous2_Active_Status (On/Off)
Rad_Fan_Status (On/Off)	Fuel_Pump_Status (On/Off)

CAN Bus Wiring

To hook a Hondata KPro 1, 2 or 3 to an AEM CD-5 or CD-7, you first have to plug the KPro Serial2CAN adapter contact into the existing ECU connector on your vehicle harness and attach the ground terminal to the ECU mounting.

Pin E24 (SEFMJ) on the ECU, which is normally used for OEM dashboard communication, needs to be removed (if present) and replaced with the Yellow wire w/terminal coming from the Serial2CAN Adapter. The Black ring terminal needs to be attached to the ECU mount.



To connect the Serial2CAN adapter top the dash, plug the adapter into the 4 pin connector on the main harness supplied with the dash and the other 4 pin connector into the power harness supplied with the dash. The Red & Black wires from the power harness should be connected to switched, fused 12V power and ground, respectively.



The AEM Serial2CAN adapter has an internal terminating resistor. As long as the adapter is on one physical end of the CAN Network and the AEM Display is on the other with its terminating resistor activated then no further action regarding terminating resistors is required on this port.

Hondata KPro Setup

The Datalogger Output must be enabled on the KPro and is done using the KManager Software.

Note that only PRB calibrations support the serial output. PRB calibrations may be used in PRB, PNF, PRD, PRC and PND ECUs with re-tuning, but cannot be used in PRA ECUs.

In KManager, in the Parameters window, select the Multiplexer/Digital Output tab, then select the Multiplexer to be "Datalogger (115,200 bps). Save the file upload as usual.

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Parameter:	5		l e u l					
Advanced /	Analog Inputs Bo	Closed Loop	Closed Loop Advance					
Digital Input	Flex Fuel Fuel Co	Fuel Injectors	Fuel Trim Gear Cor					
Idle Ignition Compensation Knock Lean Protection MAP								
Multiplexer	/ Digitial Output	litrous	1 Nitrous	2 Nitrous 3				
Notes	Unboard Dat	alogging	Protection	Rev Limits				
Shift / Shift	t Cut Th	rottle	Traction Contro	VTEC				
Multiplexer								
Datalogger	(115,200 bps)	•)	Multiplexer He				
Lotus (2005.0	2007)							
Speedometer	correction 0	%						
Shift light	0	rpm						
Lotus (2008+))							
Speedometer	correction 0	%	Shift light 1	0 rpm				
Odometer cor	rection 0	%	Shift light 2	0 rpm				
			Shift light 3	0 rpm				
-Fuel Level (FT	'P/E14)	1						
Minimum leve	0.29	v						
Maximum lev	el 4.69] v						
Digital Output	(KPro4 only)							
Туре	Disabled		•					
CAN Output (I	(Pro4 only)							

AEM Setup in DashDesign

The fastest way to get something working is to start with an AEM created setup for the KPro using the Serial2CAN adapter. These are installed with DashDesign on your computer and can be found at:

...\AEM\DashDesign\Setups\App Specific

STOP HERE

You only need to continue if you choose to not use the AEM supplied layout and wish to import KPro Serial2CAN support to custom or other existing layouts.

Adding Serial2CAN KPro support on different Layouts

If you want to create something from scratch, you can either start with a new dash layout by selecting "File" then "New" in DashDesign or you can select from a pre-designed layout that has screens already designed and inserted but has the CAN inputs left blank. These are chosen by selecting "File" then "Open" and selecting one of the setups titled xzyblank.aemcd7 with the xyz representing a description of the layouts contained in the file.

To import the Serial2CAN Hondata KPro CAN configuration into your setup you select the CAN tab from within Dash Design and choose the CAN Receive tab.

Make sure the port settings are as follows:

Show: "Port 1" Baudrate: 500 kbit/s Termination Resistor: "ON" Address Mask: "OFF" M800 Support: "OFF"

*Untitled [Modified] - AEM Dash Design									- O X		
<u>File Edit Screen View Tools Configure H</u> elp											
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CAN Receive CAN Request	t to: Set	up 🛃 /:	Graphics	 8: Simulato 	or						
Port CAN Message Layout											
Show Dart 1 - Raudrate 500 khit/c - Ramination Perinter											
	Byte 0	7	6	5	4	3	2	1	0		
Port Mode	Pote 1										
Normal Mode 🖙 Import OBDII Scan	byte 1	15	14	13	12	11	10	9	8		
MoTeC M800 Support	Byte 2					10			16		
		25	22	21	20	19	10	1/	10		
	Byte 3	31	30	29	28	27	26	25	24		
Address Mask	Byte 4										
Enabled Mask ext 0x1FFFFFF		39	38	37	36	35	34	33	32		
Show CAN IDs in Hexadecimal	Byte 5	47	46	45	44	43	42	41	40		
	Byte 6										
		55	54	53	52	51	50	49	48		
	Byte 7	62	62	61	60	50	5.0	57	56		
	Multiplexor		02				50	57			
Signal ID Start Bit Length Value	Туре	Byte Order	Multiplex	Scalar	Offset R	eciprocal	Units				
Import CAN/DBC X Clear									+ 💼		

Then click on "Import CAN" on the lower left and select the Serial2CAN Hondata KPro CAN setup file "**S2C_Hondata_KPro_Rev0.dbc**".

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CAN Receive CAN Request														
Port CAN Message Layout														
Show Port 1 - Baudrate	500 kbit/s 🔻 🔽	Termination	Resistor			EngineSpeed								
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			·		Data 2	VehicleSpeed								
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Show CAN IDs in Hexadeci	imal				oyte o	47	46	45		44	43	42	41	40
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					Multiplexo	r 🛛 🔻								
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EngineSpeed	0x660	8	16	Signed Int	eger	BE/Motorola	Off	1 0) [angular_sp	eed:rpm		
∽ VehicleSpeed	0x660	24	16	Signed Inte	eger	BE/Motorola	Off	1 () [speed:mph			
∽ GearPosCalculated	0x660	32	8	Signed Inte	eger	BE/Motorola	Off	1 0) [-
∽ ECUBatteryVoltage	0x660	40	8	Unsigned I	Integer	BE/Motorola	Off	0.1 0			voltage:V			
∽ IntakeManifoldAir l'emp	0x661	8 24	16	Signed Inte	eger	BE/Motorola	Off	1 (temperature:F			
- ThrottlePor	0x001	24	10	Signed Inte	eger	PE/Motorola	Off	1 (L T		fractions ⁹	er		
	0x662	24	16	Signed Inte	eger	BE/Motorola	Off	01 0			Traction:%			
∽ FuelIniPulsewidth	0x663	8	16	Signed Integer		BE/Motorola	Off	0.001 0			time:ms			
∽ IgnitionTiming	0x663	24	16	Signed Integer		BE/Motorola	Off	1 () [angle:deg			
∽ AFR	0x664	8	16	Signed Integer		BE/Motorola	Off	3.0518e-05 0) [afr:LA			
∽ KnockCount	0x665	8	16	Signed Inte	eger	BE/Motorola	Off	1 () [
ComIntokoDor	0.666	24	16	Cianad Int.	0005	DE /Motorola	0#	1 (1		analaidaa			
import CAN/DBC	🗙 Clear													+ 💼

The new items will appear in the table. They can now be viewed on the display or logged. You can rename, filter, or manipulate any of these channels to make them more useful.